Lock-free algorithms: The one-time initialization

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Raymond Chen

A special case of <u>the singleton constructor</u> is simply lazy-initializing a bunch of variables. In a single-threaded application you can do something like this:

```
// suppose that any valid values for a and b stipulate that 

// a \ge 0 and b \ge a. Therefore, -1 is never a valid value, 

// and we use it to mean "not yet initialized". 

int a = -1, b = -1; 

void LazyInitialize() 

{ if (a != -1) return; // initialized already 

a = calculate\_nominal\_a(); 

b = calculate\_nominal\_b(); 

// Adjust the values to conform to our constraint. 

a = max(0, a); 

b = max(a, b); 

}
```

This works fine in a single-threaded program, but if the program is multi-threaded, then two threads might end up trying to lazy-initialize the variables, and there are race conditions which can result in one thread using values before they have been initialized:

Thread 1 Thread 2

```
if (a != -1) [not taken]
a = calculate_nominal_a(); // returns
2

if (a != -1) return; // premature
return!
```

Observe that if the first thread is pre-empted after the value for **a** is initially set, the second thread will think that everything is initialized and may end up using an uninitialized **b**.

"Aha," you say, "that's easy to fix. Instead of a, I'll just use b to tell if initialization is complete."

```
void LazyInitialize()
{
  if (b != -1) return; // initialized already (test b, not a)
  a = calculate_nominal_a();
  b = calculate_nominal_b();
  // Adjust the values to conform to our constraint.
  a = max(0, a);
  b = max(a, b);
}
```

This still suffers from a race condition:

Thread 1 Thread 2

```
if (b != -1) [not taken]

a = calculate_nominal_a(); // returns
2

b = calculate_nominal_b(); // returns
1

if (b != -1) return; // premature
return!
```

"I can fix that too. I'll just compute the values of a and b in local variables, and update the globals only after the final values have been computed. That way, the second thread won't see partially-calculated values."

```
void LazyInitialize()
{
  if (b != -1) return; // initialized already
  // perform all calculations in temporary variables first
  int temp_a = calculate_nominal_a();
  int temp_b = calculate_nominal_b();
  // Adjust the values to conform to our constraint.
  temp_a = max(0, temp_a);
  temp_b = max(temp_a, temp_b);
  // make the temporary values permanent
  a = temp_a;
  b = temp_b;
}
```

Nearly there, but there is *still* a race condition:

Thread 1 Thread 2

```
if (b != -1) [not taken]

temp_a = calculate_nominal_a(); //
returns 2

temp_b = calculate_nominal_b(); //
returns 1

temp_a = max(0, temp_a); // temp_a = 2

temp_b = max(temp_a, temp_b); //
temp_b = 2

a = temp_a; // store issued to memory

b = temp_b; // store issued to memory

store of b completes to memory

if (b != -1) return; // premature return!
```

store of a completes to memory

There is no guarantee that the assignment b=2 will become visible to other processors after the assignment a=2. Even though the store operations are issued in that order, the memory management circuitry might complete the memory operations in the opposite order, resulting in Thread 2 seeing a=-1 and b=2.

To prevent this from happening, the store to **b** must be performed with <u>Release semantics</u>, indicating that all prior memory stores must complete before the store to **b** can be made visible to other processors.

```
void LazyInitialize()
if (b != -1) return; // initialized already
// perform all calculations in temporary variables first
 int temp_a = calculate_nominal_a();
int temp_b = calculate_nominal_b();
 // Adjust the values to conform to our constraint.
 temp_a = max(0, temp_a);
 temp_b = max(temp_a, temp_b);
 // make the temporary values permanent
a = temp_a;
 // since we use "b" as our indication that
// initialization is complete, we must store it last,
// and we must use release semantics.
InterlockedCompareExchangeRelease(
    reinterpret_cast<LONG*>&b, temp_b, -1);
}
```

If you look at the final result, you see that this is pretty much a re-derivation of the singleton initialization pattern: Do a bunch of calculations off to the side, then publish the result with a single InterlockedCompareExchangeRelease operation.

The general pattern is therefore

```
void LazyInitializePattern()
{
  if (global_signal_variable != sentinel_value) return;
  ... calculate values into local variables ...
  globalvariable1 = temp_variable1;
  globalvariable2 = temp_variable2;
  ...
  globalvariableN = temp_variableN;
  // publish the signal variable last, and with release
  // semantics to ensure earlier values are visible as well
  InterlockedCompareExchangeRelease(
    reinterpret_cast<LONG*>&global_signal_variable,
    temp_signal_variable, sentinel_value);
}
```

If this all is too much for you (and given some of the subtlety of double-check-locking that I messed up the first time through, it's clearly too much for me), you can let the Windows kernel team do the thinking and use the <u>one-time initialization functions</u>, which encapsulate all of this logic. (My pal <u>Doron</u> called out the one-time initialization functions <u>a while back</u>.) Version 4 of the .NET Framework has corresponding functionality in the <u>Lazy<T> class</u>.

Exercise: What hidden assumptions are being made about the functions calculate nominal a and calculate nominal b?

Exercise: What are the consequences if we use InterlockedExchange instead of InterlockedCompareExchangeRelease?

Exercise: In the final version of LazyInitialize, are the variables temp_a and temp_b really necessary, or are they just leftovers from previous attempts at fixing the race condition?

Exercise: What changes (if any) are necessary to the above pattern if the global variables are pointers? Floating point variables?

Update: See discussion below <u>between Niall and Anon</u> regarding the need for acquire semantics on the initial read.

Raymond Chen

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